

New software speed records for cryptographic pairings

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Abstract. This paper presents new software speed records for the computation of cryptographic pairings. More specifically, we present details of an implementation which computes the optimal ate pairing on a 256-bit Barreto-Naehrig curve in only 4,379,912 cycles on one core of an Intel Core 2 Quad Q9550 processor.

This speed is achieved by combining 1.) state-of-the-art high-level optimization techniques, 2.) a new representation of elements in the underlying finite fields which makes use of the special modulus arising from the Barreto-Naehrig curve construction, and 3.) implementing arithmetic in this representation using the double-precision floating-point SIMD instructions of the AMD64 architecture.

Keywords: Pairings, Barreto-Naehrig curves, ate pairing, AMD64 architecture, modular arithmetic, SIMD floating-point instructions

1 Introduction

The use of pairings in cryptography has enabled practical realizations of numerous protocols. The implementation of such protocols demands the ability to efficiently compute the pairing while guaranteeing a required level of security. Most cryptographic pairings are derived from the Tate pairing on elliptic curves.

Since the introduction of Miller's algorithm [28, 29] for computing pairings on elliptic curves, a lot of research has been devoted to finding the most efficient Tate-pairing variants for different security levels by constructing suitable pairing-friendly elliptic curves [20] and by making specific choices for the groups and parameters involved in the computation [8, 9]. Several variants of the Tate pairing

* This work has been supported in part by the European Commission through the ICT Programme under Contract ICT-2007-216499 CACE, and through the ICT Programme under Contract ICT-2007-216646 ECRYPT II. Permanent ID of this document: 4d8d6cd8dc32f9524bb84bbe9c148076. Date: July 14, 2010

have been proposed like the eta, ate and twisted ate pairings [7, 25], the R-ate [26] and optimal ate pairings [34] (see also [6]), often increasing the computational efficiency over that of their predecessors. Overall, these improvements have led to a remarkable increase in the efficiency of pairing-based protocols. Still, new protocols including the computation of a large number of pairings or pairing products [15, 23] demand even faster pairings.

Pairing-based protocols involve elliptic-curve point groups as well as subgroups of the multiplicative group of a finite field. To achieve most efficient implementations, it is desirable to choose parameters such that the discrete logarithm problems in all groups have roughly the same difficulty.

At the 128-bit security level, a nearly optimal choice for a pairing-friendly curve is a Barreto-Naehrig (BN) curve [10] over a prime field of size roughly 256 bits with embedding degree $k = 12$. According to [5], such a curve achieves 128 bits of security, while according to [17] this is 124 bits. This paper describes a constant-time implementation of an optimal ate pairing on a BN curve over a prime field \mathbb{F}_p of size 256 bits. The prime p is given by the BN polynomial parametrization $p = 36u^4 + 36u^3 + 24u^2 + 6u + 1$, where $u = v^3$ and $v = 1868033$. The curve equation is $E : y^2 = x^3 + 3$.

We are the first to propose a software pairing implementation exploiting the polynomial parametrization of the prime p to speed up the underlying field arithmetic. For most pairing-friendly curves, the primes defining the base field are constructed using polynomial parametrizations. These parametrizations have been used to speed up the final exponentiation [33], but so far have not been successfully exploited for field arithmetic in software. Nevertheless, Fan, Vercauteren, and Verbauwhede [18] use the polynomial shape of the prime p to achieve computational speedups in hardware.

To maximize reusability of our results we put all software⁴ described in this paper into the public domain.

Related work. There exist several descriptions and benchmarks of software implementations of cryptographic pairings. Implementations targeting the 128-bit security level usually use 256-bit BN curves.

The software presented in [24] takes 10,000,000 cycles to compute the R-ate pairing over a 256-bit BN curve on one core of an Intel Core 2 processor; the same computation on one core of an AMD Opteron processor also takes 10,000,000 cycles. Unpublished benchmarks of a newer version of that software (included in the Miracl library [27]) are claimed to take 7,850,000 cycles on an Intel Core 2 Duo T5500 processor [32]. The software presented in [31] takes 29,650,000 cycles to compute the ate pairing over a 256-bit BN curve on one core of a Core 2 Duo processor. Software presented in [21] takes 23,319,673 cycles to compute the ate pairing over a 256-bit BN curve on one core of an Intel Core 2 Duo processor; another implementation described in the same paper takes 14,429,439 to compute the ate pairing on two cores of an Intel Core 2 Duo processor. The software presented in [3] also targets the 128-bit security level and computes the η_T pairing on a supersingular curve over a binary field in 17,400,000 cycles on one

⁴ Available at <http://www.cryptojedi.org/crypto/#dclxvi>.

core of a 45 nm Intel Core 2. processor. The paper also presents performance numbers of the same pairing computation on multiple cores, for example the computation on 4 cores of a 45 nm Intel Core 2 processor takes 5,080,000 cycles, on 8 cores it takes 3,020,000 cycles.

The software presented in this paper computes the optimal ate pairing in 4,379,912 cycles on one core of an Intel Core 2 Quad Q9550 processor and is thus more than twice as fast as the fastest previously published result and more than 40 percent faster than previous unpublished results we are aware of.

A paper published later and partially building on our results achieves even better performance [14]. It describes an implementation of the optimal ate pairing on a 254-bit BN curve which takes 3,320,000 cycles on an Intel Core 2 T7100 processor and only 2,630,000 cycles on an Intel Core i7 860 processor. This implementation uses Montgomery arithmetic in \mathbb{F}_p implemented using 64-bit integer-arithmetic instructions.

Organization of the paper. In Section 2 we give a short review of the optimal ate pairing for BN curves. Section 3 collects state-of-the-art high-level optimization techniques for the computation of cryptographic pairings on BN curves from the literature as we use them in our software. Section 4 describes our new approach to represent elements of the underlying finite field \mathbb{F}_p and algorithms to perform arithmetic using this representation in \mathbb{F}_p and \mathbb{F}_{p^2} . In Section 5 we explain how we use the double-precision floating-point SIMD instructions of the AMD64 instruction set (SSE, SSE2, SSE3) to efficiently implement these algorithms. Section 6 gives benchmarking results of our software on different microarchitectures.

2 An optimal ate pairing over Barreto-Naehrig curves

For a Barreto-Naehrig (BN) curve, the most efficient pairings are the R-ate pairing [26] and optimal ate pairings [34]. In this section, we provide the basic background and notation, and describe the algorithm for an optimal ate pairing that is used in our implementation.

Let $E : y^2 = x^3 + b$ be a BN curve over the prime field \mathbb{F}_p . This means that there is a $u \in \mathbb{Z}$ such that both p and n , given by

$$\begin{aligned} p &= p(u) = 36u^4 + 36u^3 + 24u^2 + 6u + 1, \\ n &= n(u) = 36u^4 + 36u^3 + 18u^2 + 6u + 1, \end{aligned}$$

are prime. The number of \mathbb{F}_p -rational points on E is $\#E(\mathbb{F}_p) = n$, and E has embedding degree $k = 12$ with respect to n . We denote by \mathcal{O} the point at infinity, i.e. the neutral element of the group operation on E . For $m \in \mathbb{Z}$, we write $[m]$ for the multiplication-by- m map on E .

Let ϕ_p be the p -power Frobenius endomorphism on E and $E[n]$ the n -torsion subgroup of E . We define $G_1 = E[n] \cap \ker(\phi_p - [1]) = E(\mathbb{F}_p)$, $G_2 = E[n] \cap \ker(\phi_p - [p]) \subseteq E(\mathbb{F}_{p^{12}})[n]$, $G_3 = \mu_n$, where $\mu_n \subset \mathbb{F}_{p^{12}}^*$ is the group of n -th roots of unity.

An optimal ate pairing on E is given in [34] as

$$a_{\text{opt}} : G_2 \times G_1 \rightarrow G_3, (Q, P) \mapsto (f_{6u+2, Q}(P) \cdot g_{6u+2, Q}(P))^{(p^{12}-1)/n},$$

where $g_{6u+2, Q}(P) = l_{Q_3, -Q_2}(P) \cdot l_{-Q_2+Q_3, Q_1}(P) \cdot l_{Q_1-Q_2+Q_3, [6u+2]Q}(P)$ with $Q_1 = \phi_p(Q)$, $Q_2 = \phi_p^2(Q)$, and $Q_3 = \phi_p^3(Q)$. The value $l_{R, S}(P) \in \mathbb{F}_{p^{12}}$ is the function of the line through the points R and S on the curve, evaluated at P .

There is no need to compute Q_3 . Instead, $g_{6u+2, Q}(P)$ can be replaced by

$$h_{6u+2, Q}(P) = l_{[6u+2]Q, Q_1}(P) \cdot l_{[6u+2]Q+Q_1, -Q_2}(P).$$

The reason for this is that for BN curves $Q_1 - Q_2 + Q_3 + [6u+2]Q = \mathcal{O}$, which can be easily derived from Lemma 2.17 in [30]. By writing down the divisors of the functions $g_{6u+2, Q}$ and $h_{6u+2, Q}$, it can be seen that they only differ by vertical line functions. When evaluated at P , such line functions produce values in proper subfields of $\mathbb{F}_{p^{12}}$ that are mapped to 1 by the final exponentiation.

Algorithm 1 Optimal ate pairing on BN curves for $u > 0$

Input: $P \in G_1$, $Q \in G_2$, $m_{\text{opt}} = 6u + 2 = (1, m_{s-1}, \dots, m_0)_{\text{NAF}}$, $m_i \in \{-1, 0, 1\}$.

Output: $a_{\text{opt}}(Q, P)$.

```

1:  $R \leftarrow Q$ ,  $f \leftarrow 1$ 
2: for ( $i \leftarrow s - 1$ ;  $i \geq 0$ ;  $i --$ ) do
3:    $f \leftarrow f^2 \cdot l_{R, R}(P)$ ,  $R \leftarrow [2]R$ 
4:   if ( $m_i = -1$ ) then
5:      $f \leftarrow f \cdot l_{R, -Q}(P)$ ,  $R \leftarrow R - Q$ 
6:   else if ( $m_i = 1$ ) then
7:      $f \leftarrow f \cdot l_{R, Q}(P)$ ,  $R \leftarrow R + Q$ 
8:   end if
9: end for
10:  $Q_1 = \phi_p(Q)$ ,  $Q_2 = \phi_{p^2}(Q)$ 
11:  $f \leftarrow f \cdot l_{R, Q_1}(P)$ ,  $R \leftarrow R + Q_1$ 
12:  $f \leftarrow f \cdot l_{R, -Q_2}(P)$ ,  $R \leftarrow R - Q_2$ 
13:  $f \leftarrow f^{p^6-1}$ 
14:  $f \leftarrow f^{p^2+1}$ 
15:  $f \leftarrow f^{(p^4-p^2+1)/n}$ 
16: return  $f$ 

```

Algorithm 1 shows how $a_{\text{opt}}(Q, P)$ can be computed in the case $u > 0$ and when m_{opt} is given in non-adjacent form (NAF). Lines 2 to 9 are called the Miller loop. It contains doubling steps in Line 3 and addition steps in Lines 5 and 7. The value $h_{6u+2, Q}(P)$ is multiplied to the result of the Miller loop in Lines 10 to 12 by two addition steps. Lines 13 to 15 together carry out the final exponentiation to the power $(p^{12} - 1)/n$, where Lines 13 and 14 comprise its easy part. It can be done by applying the p^6 -power Frobenius automorphism on $\mathbb{F}_{p^{12}}$, a single inversion and a multiplication in $\mathbb{F}_{p^{12}}$. Line 15 represents the hard part of the final exponentiation.

As usual [10, 25, 16], we use a sextic twist $E' : y^2 = x^3 + b/\xi$ defined over \mathbb{F}_{p^2} to represent the points in G_2 by points on the twist using the twist isomorphism $\psi : E' \rightarrow E$, $(x', y') \mapsto (\omega^2 x', \omega^3 y')$. The element $\xi \in \mathbb{F}_{p^2}$ (neither a cube nor a square in \mathbb{F}_{p^2}) is chosen such that the twist has the right order, i.e. it holds $n \mid \#E'(\mathbb{F}_{p^2})$. The field $\mathbb{F}_{p^{12}}$ is generated over \mathbb{F}_{p^2} by ω via the irreducible polynomial $X^6 - \xi$, i.e. $\omega^6 = \xi$.

The map ψ induces a group isomorphism between $G'_2 = E'(\mathbb{F}_{p^2})[n]$ and G_2 . So, all points $R \in G_2$ should be seen as being represented by a corresponding point $R' \in G'_2$, i.e. $R = \psi(R')$. All curve arithmetic is done on the twist and intermediate results can be kept in their representation on E' . This means that all curve arithmetic requires \mathbb{F}_{p^2} -arithmetic only. Arithmetic in $\mathbb{F}_{p^{12}}$ is also based on arithmetic in \mathbb{F}_{p^2} . Overall, there are no \mathbb{F}_p computations other than those involved in \mathbb{F}_{p^2} computations during the optimal-ate-pairing algorithm. Thus an improvement of \mathbb{F}_{p^2} -arithmetic—even without improving \mathbb{F}_p -arithmetic—leads to an improvement of all parts of the computation.

3 High-level techniques: field extensions, Miller loop and final exponentiation

In this section, we describe the high-level structure of our implementation. We use state-of-the-art optimization techniques from the literature for this implementation level. Our focus is on the construction of the higher degree field extensions such as \mathbb{F}_{p^6} and $\mathbb{F}_{p^{12}}$, the Miller loop to compute $f_{6u+2,Q}(P)$, the function value $h_{6u+2,Q}(P)$ and the structure of the final exponentiation.

The construction of field extensions and the efficiency of the optimal ate pairing depend on the chosen curve parameters. Since our new base-field representation needs the parameter u to be a third power $u = v^3$, we are strongly restricted in the choice of curves. Field multiplications and squarings in $\mathbb{F}_{p^{12}}$ are very expensive, so another important condition on u is that $6u + 2$ should have a Hamming weight as low as possible, to save as many addition steps during the Miller loop as possible.

Our specific choice here is $u = v^3$ with $v = 1868033$. This value provides a low NAF weight for $6u + 2$ together with a good addition-subtraction chain for exponentiation with u for use in the final exponentiation. All ideas in this paper also work for other choices of v , but might lead to less efficient implementations.

3.1 Field extensions

The above choice for u implies $p \equiv 3 \pmod{4}$ which means that the field extension \mathbb{F}_{p^2} can be constructed as $\mathbb{F}_{p^2} = \mathbb{F}_p(i)$, where $i^2 = -1$. The value ξ to construct the twist and higher-degree extensions is $\xi = i + 3$.

On top of the quadratic extension we build the field $\mathbb{F}_{p^{12}}$ as a tower, first $\mathbb{F}_{p^6} = \mathbb{F}_{p^2}(\tau)$ with $\tau^3 = \xi$ and then $\mathbb{F}_{p^{12}} = \mathbb{F}_{p^6}(\omega)$ with $\omega^2 = \tau$. This is the same construction as in [16] and we follow [16] in implementing the extension field arithmetic.

3.2 Miller loop

The value $6u + 2$ determines the number of doubling and addition steps in the Miller loop of the optimal ate pairing. The number of doubling steps is 65. The NAF weight of $6u + 2$ is 19, so there are 18 addition steps. Throughout the pairing computation we use the group G'_2 to represent points in G_2 . We use Jacobian coordinates for the curve arithmetic in G'_2 . In particular, for the doubling and addition steps, we use the formulas given by Arène et al. in [4]. The points in G_1 , at which line functions are evaluated, are kept in affine coordinates.

The multiplication of the intermediate variable f with the line function values in the Miller loop is done via a special multiplication function exploiting the fact that line function values are sparse elements of $\mathbb{F}_{p^{12}}$, where only half of the coefficients over \mathbb{F}_{p^2} are different from zero.

After the Miller loop, the points Q_1 and Q_2 are computed by applying the p -power and the p^2 -power Frobenius endomorphisms. We do two final addition steps with Q_1 and $-Q_2$, respectively, to multiply the result of the Miller loop by the function value $h_{6u+2,Q}(P)$.

3.3 Final exponentiation

The final exponentiation in our implementation is done as indicated in Lines 13 to 15 of Algorithm 1. It is divided into the easy part (Lines 13, 14) and the hard part (Line 15). The easy part has low computational costs compared to the hard part. Raising the element to the power $p^6 - 1$ is simply a conjugation in the extension $\mathbb{F}_{p^{12}}/\mathbb{F}_{p^6}$ and a single division in $\mathbb{F}_{p^{12}}$. The exponentiation by $p^2 + 1$ is done by applying the p^2 -power Frobenius automorphism and one multiplication.

Note that after the easy part of the final exponentiation, the resulting element in $\mathbb{F}_{p^{12}}$ lies in the cyclotomic subgroup of $\mathbb{F}_{p^{12}}^*$, i.e. the subgroup of order $\Phi_{12}(p) = p^4 - p^2 + 1$, where Φ_{12} is the 12-th cyclotomic polynomial. Granger and Scott [22] recently showed how to exploit this fact to obtain very efficient squaring formulas for such elements. We use these formulas during the hard part of the final exponentiation. Furthermore, the inverse of an element in the cyclotomic subgroup can be computed by a conjugation over \mathbb{F}_{p^6} , which means that inversions are essentially for free.

For the hard part, we use the method proposed by Scott et al. in [33]. The main advantage here is that the exponentiation is essentially split into three exponentiations by the exponent $u = v^3$, each implemented as three exponentiations by v . The latter can be done with 21 special squarings and 4 multiplications in $\mathbb{F}_{p^{12}}$ by using an addition-subtraction chain as shown in Algorithm 2.

In the end, the final result is obtained by applying the Frobenius automorphism and by using the polynomial representation in u of the fixed exponent $(p^4 - p^2 + 1)/n$.

Algorithm 2 Exponentiation by $v = 1868033$ **Input:** $a \in \mathbb{F}_{p^{12}}$.**Output:** a^v .

```

1:  $t_0 \leftarrow a^8$ 
2:  $t_1 \leftarrow t_0^8$ 
3:  $t_2 \leftarrow t_0^{-1}$ 
4:  $t_2 \leftarrow t_2 \cdot a$ 
5:  $t_2 \leftarrow t_2 \cdot t_1$ 
6:  $t_2 \leftarrow t_2^{128}$ 
7:  $t_2 \leftarrow t_2 \cdot a$ 
8:  $t_2 \leftarrow t_2^{256}$ 
9:  $t_2 \leftarrow t_2 \cdot a$ 
10: return  $t_2$ 

```

4 Mid-level techniques: arithmetic in \mathbb{F}_{p^2} and \mathbb{F}_p

This section explains the new approach for representing integers modulo p where p is given by the BN polynomial $36u^4 + 36u^3 + 24u^2 + 6u + 1$. Inspired by Bernstein's implementation of Curve25519 [13], we suggest to split such an integer into 12 coefficients each of which will be stored in a double-precision floating-point variable in the software implementation. We now give the details of our approach.

4.1 Representing base field elements

Elements in the base field \mathbb{F}_p are integers modulo the prime $p = 36u^4 + 36u^3 + 24u^2 + 6u + 1$ for some $u \in \mathbb{Z}$. The technique in this section does not depend on the specific fixed value for u that we chose in our implementation. We only need to make the assumption that there exists an integer $v \in \mathbb{Z}$ with $u = v^3$. Furthermore, let $\delta = \sqrt[6]{6}$. Then we have $(\delta vx)^3 = \sqrt{6}ux^3$.

We represent integers by polynomials in the ring

$$R = \mathbb{Z}[x] \cap \overline{\mathbb{Z}}[\delta vx],$$

where $\overline{\mathbb{Z}}$ denotes the ring of algebraic integers in \mathbb{C} . Note that the ring homomorphism $R \mapsto \mathbb{Z}$, $F \mapsto f = F(1)$ is surjective and thus we may represent an integer f by any polynomial F in the preimage of f under the above map. The product of two integers can be computed by multiplying the corresponding polynomials in R and evaluating the product at 1.

Since δ is an algebraic integer, we see that the polynomial

$$\begin{aligned} P &= 36u^4x^{12} + 36u^3x^9 + 24u^2x^6 + 6ux^3 + 1 \\ &= (\delta vx)^{12} + \delta^3(\delta vx)^9 + 4(\delta vx)^6 + \delta^3(\delta vx)^3 + 1 \end{aligned}$$

is an element of R representing the prime p .

Let $\alpha = \delta vx$. Any integer f can be represented by a polynomial $F \in R$ with $F(1) = f$ of the following form:

$$\begin{aligned} F &= f_0 + f_1\delta^5\alpha + f_2\delta^4\alpha^2 + f_3\delta^3\alpha^3 + f_4\delta^2\alpha^4 + f_5\delta\alpha^5 \\ &\quad + f_6\alpha^6 + f_7\delta^5\alpha^7 + f_8\delta^4\alpha^8 + f_9\delta^3\alpha^9 + f_{10}\delta^2\alpha^{10} + f_{11}\delta\alpha^{11} \\ &= f_0 + f_1 \cdot 6(vx) + f_2 \cdot 6(vx)^2 + f_3 \cdot 6(vx)^3 + f_4 \cdot 6(vx)^4 \\ &\quad + f_5 \cdot 6(vx)^5 + f_6 \cdot 6(vx)^6 + f_7 \cdot 36(vx)^7 + f_8 \cdot 36(vx)^8 \\ &\quad + f_9 \cdot 36(vx)^9 + f_{10} \cdot 36(vx)^{10} + f_{11} \cdot 36(vx)^{11}, \end{aligned}$$

where $f_i \in \mathbb{Z}$ for all i . The integer f corresponds to the vector of coefficients $(f_0, f_1, \dots, f_{11})$ of F .

4.2 Multiplication modulo p

Multiplication modulo p in the new representation is done in two stages, first a polynomial multiplication of the two polynomials representing the integers and second a reduction step.

Let $f, g \in \mathbb{Z}$ be two integers with corresponding polynomials $F, G \in R$ and coefficient vectors $(f_0, f_1, \dots, f_{11})$ and $(g_0, g_1, \dots, g_{11})$. The product $H = FG$ then has coefficient vector $(h_0, h_1, \dots, h_{22})$ and has the form $H = h_0 + h_1\delta^5\alpha + \dots + h_{21}\delta^2\alpha^{21} + h_{22}\delta\alpha^{22}$.

We next represent the result of the multiplication by a polynomial of degree 11 which has 12 coefficients. For the degree-reduction, we use the polynomial P representing the BN prime p . Reducing polynomials modulo P corresponds to reducing the corresponding integers modulo p . We have $P = \alpha^{12} + \delta^3\alpha^9 + 4\alpha^6 + \delta^3\alpha^3 + 1$, thus we can use the equation

$$\alpha^{12} = -\delta^3\alpha^9 - 4\alpha^6 - \delta^3\alpha^3 - 1$$

to reduce the degree of H . The degree reduction is given in Algorithm 3.

Polynomial multiplication and degree reduction make the coefficients grow in their absolute value. Whenever the coefficients get too large we need to do a coefficient reduction. For that we use Algorithm 4. We address the relevant bounds on the coefficients and how to guarantee them in Section 5.1. After the reduction, we have

$$h_0, h_6 \in [-|3v|, |3v|), \quad h_1, h_3, h_4, h_7, h_9, h_{10} \in [-|v/2|, |v/2|),$$

the coefficients h_2, h_5, h_8, h_{11} may have an absolute value only slightly larger than $|v/2|$. The function `rnd` in Algorithm 4 denotes rounding to the nearest integer.

5 Low-level techniques: using SIMD floating-point arithmetic

Implementations of large-integer arithmetic on 64-bit processors usually decompose a large integer into limbs of 64 bits. Arithmetic is then performed using

Algorithm 3 Degree reduction after polynomial multiplication**Input:** Coefficient vector $(h_0, h_1, \dots, h_{22}) \in \mathbb{Z}^{23}$ of $H \in R$ with $H(1) = h$.**Output:** Reduced coefficient vector $(h'_0, h'_1, \dots, h'_{11})$ of H' with $H'(1) = h$.

- 1: $h'_0 \leftarrow h_0 - h_{12} + 6h_{15} - 2h_{18} - 6h_{21}$
- 2: $h'_1 \leftarrow h_1 - h_{13} + h_{16} - 2h_{19} - h_{22}$
- 3: $h'_2 \leftarrow h_2 - h_{14} + h_{17} - 2h_{20}$
- 4: $h'_3 \leftarrow h_3 - h_{12} + 5h_{15} - h_{18} - 8h_{21}$
- 5: $h'_4 \leftarrow h_4 - 6h_{13} + 5h_{16} - 6h_{19} - 8h_{22}$
- 6: $h'_5 \leftarrow h_5 - 6h_{14} + 5h_{17} - 6h_{20}$
- 7: $h'_6 \leftarrow h_6 - 4h_{12} + 18h_{15} - 3h_{18} - 30h_{21}$
- 8: $h'_7 \leftarrow h_7 - 4h_{13} + 3h_{16} - 3h_{19} - 5h_{22}$
- 9: $h'_8 \leftarrow h_8 - 4h_{14} + 3h_{17} - 3h_{20}$
- 10: $h'_9 \leftarrow h_9 - h_{12} + 2h_{15} + h_{18} - 9h_{21}$
- 11: $h'_{10} \leftarrow h_{10} - 6h_{13} + 2h_{16} + 6h_{19} - 9h_{22}$
- 12: $h'_{11} \leftarrow h_{11} - 6h_{14} + 2h_{17} + 6h_{20}$
- 13: **return** $(h'_0, h'_1, \dots, h'_{11})$.

Algorithm 4 Coefficient reduction**Input:** Coefficient vector $(h_0, h_1, \dots, h_{11}) \in \mathbb{Z}^{12}$ of $H \in R$ with $H(1) = h$.**Output:** Reduced coefficient vector $(h'_0, h'_1, \dots, h'_{11})$ of H' with $H'(1) = h$.

- 1: $r \leftarrow \text{rnd}(h_1/v), h_1 \leftarrow h_1 - rv, h_2 \leftarrow h_2 + r$
- 2: $r \leftarrow \text{rnd}(h_4/v), h_4 \leftarrow h_4 - rv, h_5 \leftarrow h_5 + r$
- 3: $r \leftarrow \text{rnd}(h_7/v), h_7 \leftarrow h_7 - rv, h_8 \leftarrow h_8 + r$
- 4: $r \leftarrow \text{rnd}(h_{10}/v), h_{10} \leftarrow h_{10} - rv, h_{11} \leftarrow h_{11} + r$
- 5: $r \leftarrow \text{rnd}(h_2/v), h_2 \leftarrow h_2 - rv, h_3 \leftarrow h_3 + r$
- 6: $r \leftarrow \text{rnd}(h_5/v), h_5 \leftarrow h_5 - rv, h_6 \leftarrow h_6 + r$
- 7: $r \leftarrow \text{rnd}(h_8/v), h_8 \leftarrow h_8 - rv, h_9 \leftarrow h_9 + r$
- 8: $r \leftarrow \text{rnd}(h_{11}/v), h_{11} \leftarrow h_{11} - rv$
- 9: $h_9 \leftarrow h_9 - r$
- 10: $h_6 \leftarrow h_6 - 4r$
- 11: $h_3 \leftarrow h_3 - r$
- 12: $h_0 \leftarrow h_0 - r$
- 13: $r \leftarrow \text{rnd}(h_0/(6v)), h_0 \leftarrow h_0 - r \cdot 6v, h_1 \leftarrow h_1 + r$
- 14: $r \leftarrow \text{rnd}(h_3/v), h_3 \leftarrow h_3 - rv, h_4 \leftarrow h_4 + r$
- 15: $r \leftarrow \text{rnd}(h_6/(6v)), h_6 \leftarrow h_6 - r \cdot 6v, h_7 \leftarrow h_7 + r$
- 16: $r \leftarrow \text{rnd}(h_9/v), h_9 \leftarrow h_9 - rv, h_{10} \leftarrow h_{10} + r$
- 17: $r \leftarrow \text{rnd}(h_1/v), h_1 \leftarrow h_1 - rv, h_2 \leftarrow h_2 + r$
- 18: $r \leftarrow \text{rnd}(h_4/v), h_4 \leftarrow h_4 - rv, h_5 \leftarrow h_5 + r$
- 19: $r \leftarrow \text{rnd}(h_7/v), h_7 \leftarrow h_7 - rv, h_8 \leftarrow h_8 + r$
- 20: $r \leftarrow \text{rnd}(h_{10}/v), h_{10} \leftarrow h_{10} - rv, h_{11} \leftarrow h_{11} + r$
- 21: **return** $(h'_0, h'_1, \dots, h'_{11})$.

fast 64-bit integer-multiply and -add instructions [1, 27, 2]. For our implementation we do not make use of these instructions but instead use double-precision floating-point arithmetic. Many modern microprocessors including all microprocessors implementing the AMD64 architecture have very fast floating-point units.

This is due to the fact that the performance of many applications such as image and video processing relies on fast floating-point arithmetic rather than integer processing and that many CPU benchmarks focus on the speed of floating-point operations.

It has been shown before that one can use these fast floating-point units for high-speed cryptography and for arithmetic on large integers, see for example Bernstein in [13] and [12]. In contrast to the implementation in [13] which uses 80-bit floating-point values (with a 64-bit mantissa), we decided to use 64-bit floating-point values (with a 53-bit mantissa). This allows us to use the single-instruction multiple-data (SIMD) instructions of the SSE2 and SSE3 instruction set operating on double-precision (64-bit) floating-point values.

These instructions perform two double-precision floating-point operations at once on two independent inputs layed out in 128-bit vector registers called XMM registers. The AMD64 architecture defines 16 architectural XMM registers. For example the instruction `addpd %xmm1, %xmm2` takes the low 64 bits from register `%xmm1` and the low 64 bits of register `%xmm2`, adds them as double-precision floating-point values and stores the result in the low 64 bits of register `%xmm2`; at the same time it takes the high 64 bits from register `%xmm1` and the high 64 bits of register `%xmm2`, adds them as double-precision floating-point values and stores the result in the high 64 bits of register `%xmm2`.

The most important SSE2 instructions for our implementation are the `addpd` and the `mulpd` instructions. The Intel Core 2 processors (both, 65 nm and 45 nm models) can issue up to one `mulpd` and one `addpd` instruction per cycle and thus execute 4 floating-point operations in one cycle. However, it can not execute 2 `mulpd` or 2 `addpd` instructions in the same cycle (for details see [19]). To arrange data in the XMM vector registers our implementation requires additional non-arithmetic instructions such as `shufpd`, `unpckhpd` and `unpcklpd`. In the implementation of the squaring in \mathbb{F}_{p^2} we also need the `addsd` instruction which adds the low double values of two XMM registers and leaves the high double value of the destination register unchanged.

Note that all arithmetic instructions only have 2 operands, one of the inputs is overwritten by the output. This sometimes requires additional `mov` instructions to copy data to other registers or memory.

5.1 Avoiding overflows

Double-precision floating point registers hold real numbers of the form $2^e f$, with $f \in \{-2^{53}-1, \dots, 2^{53}-1\}$ and $e \in \{-1022, \dots, 1023\}$. The result of an operation on two such numbers is guaranteed to be exact if it is in $\{-2^{53}-1, \dots, 2^{53}-1\}$, otherwise the result value may *overflow*. To make sure that such overflows do not occur, we cannot simply run the code on some inputs and check whether it produces the correct results; we have to make sure that an overflow cannot occur for any valid inputs.

We first implemented all algorithms in the C++ programming language (not using SIMD instructions) and replace the `double` data type by a self-written class `CheckDouble` to represent 64-bit floating-point values. This class performs

all arithmetic operations on a member variable d of type `double`. Furthermore it stores the “worst-case” absolute value of the mantissa m in a member variable of type `uint64_t` which is updated with each operation. Before actually performing an operation it checks whether the worst-case result overflows; if it does, the program is aborted. Updating m is straight-forward: Multiplying (d_1, m_1) and (d_2, m_2) yields (d_1d_2, m_1m_2) , adding (d_1, m_1) and (d_2, m_2) yields $(d_1 + d_2, m_1 + m_2)$, and subtracting (d_1, m_1) from (d_2, m_2) yields $(d_2 - d_1, m_1 + m_2)$. The only divisions are by the constants v and $6v$, for those divisions it is safe to set the result to $(d/v, |m/v|)$ or $(d/6v, |m/6v|)$ respectively. The remainder of a (rounding) division by v is always between $-|v/2|$ and $|v/2|$, so we can just set the maximal mantissa to $|v/2|$ when computing the remainder of a division by v . Analogously, the maximal mantissa of the remainder of a division by $6v$ is $|3v|$.

For all constants involved in the pairing computation we can initialize the maximal mantissa with the actual value. For the inputs to the pairing we assume that they are worst-case output of the reduction described in Algorithm 4.

In order to obtain the targeted performance we replaced the `CheckDouble` class again by the `double` data type and re-implemented the speed-critical functions in the `qasm` programming language [11] using SIMD instructions where possible. The operations on double-precision floating-point values in this `qasm` implementation are the same as in the C version for which we automatically verified that no overflows can occur. Tools to verify this property on the assembly level would be very helpful but we do not know of such tools. The resulting software has passed a bilinearity and non-degeneracy test on 1,000,000 random inputs, each test involving 3 pairing computations.

5.2 Implementation of field-arithmetic operations

The 12 coefficients f_0, \dots, f_{11} of a polynomial F representing an element $f \in \mathbb{F}_p$ (see Section 4) are stored consecutively in a `double` array of size 12. The 24 coefficients g_0, \dots, g_{11} and h_0, \dots, h_{11} representing an element $(gi + h) \in \mathbb{F}_{p^2}$ are stored interleaved in a `double` array of size 24 as $(h_0, g_0 | h_1, g_1 | \dots | h_{11}, g_{11})$. In the following descriptions, all SIMD instructions operate on every two adjacent double values of this representation. Observe that the implementations do not minimize the number of *instructions* but try to minimize the number of *cycles*.

$\mathbb{F}_{p^2} \times \mathbb{F}_{p^2}$ multiplication. Multiplication of $ai + b$ and $ci + d$, layed out in memory as $op_1 = (b_0, a_0 | \dots | b_{11}, a_{11})$ and $op_2 = (d_0, c_0 | \dots | d_{11}, c_{11})$, is done by duplicating b_0, \dots, b_{11} to obtain

$$t_1 = (b_0, b_0 | b_1, b_1 | \dots | b_{11}, b_{11}).$$

We then perform a digit-sliced multiplication of t_1 and op_2 to obtain

$$t_2 = (bd_0, bc_0 | \dots | bd_{22}, bc_{22}).$$

In a second step we duplicate a_0, \dots, a_{11} , obtain

$$t_1 = (a_0, a_0 | a_1, a_1 | \dots | a_{11}, a_{11}),$$

multiply digit-sliced with op_2 and obtain

$$t_3 = (ad_0, ac_0 | \dots | ad_{22}, ac_{22}).$$

We then multiply the high double values of t_3 by $i^2 = -1$ and obtain

$$t_3 = (ad_0, -ac_0 | \dots | ad_{22}, -ac_{22}).$$

Swapping in t_3 yields

$$t_3 = (-ac_0, ad_0 | \dots | -ac_{22}, ad_{22}).$$

Finally we add t_3 to t_2 and apply polynomial reduction (Algorithm 3) and coefficient reduction (Algorithm 4) to obtain interleaved coefficients of $(ai+b)(ci+d) = ((ad+bc)i + (bd-ac))$. During this computation we keep values in XMM registers as much as possible.

The parallel digit-sliced multiplication uses the schoolbook algorithm resulting in 144 multiplications (`mulpd`), 121 additions (`addpd`), and 10 more multiplications by 6 (`mulpd`). We experimented with Karatsuba multiplication but did not gain any performance – we are planning to further examine possible speedups by using Karatsuba multiplication.

Computing the rounded quotient and the remainder in the coefficient reduction could be done using multiplication by $1/v$, using the `roundpd` instruction on the result, multiplying by v and subtracting the result from the original value to obtain the remainder. As the `roundpd` instruction is part of the SSE4.1 instruction set which is not available on 65 nm Core 2 processors and all AMD processors we decided to implement rounding as addition and subsequent subtraction of a constant as explained for example by Bernstein in [12].

\mathbb{F}_{p^2} squaring. When squaring an element $ai + b \in \mathbb{F}_{p^2}$, layed out in memory as $op_1 = (b_0, a_0 | \dots | b_{11}, a_{11})$, we swap the coefficients to obtain

$$t_1 = (a_0, b_0 | \dots | a_{11}, b_{11}).$$

We use the `subsd` instruction on op_1 and t_1 to obtain

$$op_1 = (b_0 - a_0, a_0 | \dots | b_{11} - a_{11}, a_{11}).$$

Then we copy t_1 and duplicate the high double values to obtain

$$t_2 = (b_0, b_0 | \dots | b_{11}, b_{11}).$$

Adding t_1 and t_2 yields

$$t_2 = (b_0 + a_0, 2b_0 | \dots | b_{11} + a_{11}, 2b_{11}).$$

Now we use digit-sliced multiplication on op_1 and t_2 to obtain

$$r = (((b-a)(a+b))_0, 2ab_0 | \dots | ((b-a)(a+b))_{22}, 2ab_{22}).$$

Applying polynomial reduction and coefficient reduction yields the coefficients of the result $(2ab)i + (b^2 - a^2)$.

$\mathbb{F}_{p^2} \times \mathbb{F}_p$ multiplication. Evaluating the line functions requires multiplications of an element of \mathbb{F}_{p^2} with an element of \mathbb{F}_p . This is implemented using the same parallel schoolbook multiplication which is used in the $\mathbb{F}_{p^2} \times \mathbb{F}_{p^2}$ multiplication. This requires first duplicating the coefficients of the \mathbb{F}_p element in memory.

\mathbb{F}_{p^2} short coefficient reduction. Additions, subtractions and multiplications with small constants in \mathbb{F}_{p^2} can all be implemented using 12 SIMD instructions. They produce results which may have coefficients that are too large to go as input into a multiplication but are still so small that they do not require the full-fledged coefficient reduction from Algorithm 4. If the output of an addition or subtraction is used as input to a multiplication we apply a short coefficient reduction which first carries from f_{11} to f_0, f_3, f_6 and f_9 . Then it carries from all odd coefficients f_1, f_3, \dots, f_9 and then from all even coefficients f_0, f_2, \dots, f_{10} .

\mathbb{F}_p inversion. The final exponentiation involves one inversion in $\mathbb{F}_{p^{12}}$. This can be computed with only one inversion in \mathbb{F}_p and several multiplications as described in, e.g., [24, Sec. 2]. We implement inversion in \mathbb{F}_p as exponentiation with $p - 2$ using a simple square-and-multiply algorithm. There exist certainly faster methods to compute inverses in \mathbb{F}_p , but this way we can easily ensure constant-time behaviour of the inversion and the single inversion in \mathbb{F}_{p^2} accounts for less than 3 percent of the total computation time.

6 Benchmarking results

This section gives benchmarking results of the pairing computation on different microarchitectures. All benchmarks were obtained by computing the average of 50 function calls and then the median of 100 of such averages. The call to the function reading the cycle counter and the loop control incurs some overhead so Table 2 also gives the cycles obtained when no function is called between two consecutive cycle counts. The counts for the Miller loop in Table 2 include the two final addition steps in the optimal ate pairing before the final exponentiation.

Acknowledgements: We thank Tanja Lange and the anonymous referees for their valuable comments that helped us improve the paper.

We thank the authors of [14], in particular Francisco Rodríguez-Henríquez and Jean-Luc Beuchat for pointing out an error in previous versions of paper and software. In the course of fixing this bug, we were able to further improve the efficiency of our software.

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Name	Affiliation	CPU	OS	Compiler
dauzac	Eindhoven University of Technology	Intel Core 2 Quad Q6600 2404.268 MHz	Linux 2.6.28	gcc 4.3.3
behemoth	National Taiwan University	Intel Core 2 Quad Q9550 2830 MHz	Linux 2.6.27	gcc 4.3.2
dragon	National Taiwan University	Intel Xeon E5504 2000 MHz	Linux 2.6.27	gcc 3.4.6
chukonu	University of Illinois at Chicago	AMD Phenom II X4 955 3210.298 MHz	Linux 2.6.31	gcc 4.4.1

Table 1. Machines used for benchmarking

	dauzac	behemoth	dragon	chukonu
$\mathbb{F}_{p^2} \times \mathbb{F}_{p^2}$ multiplication	636	635	667	651
\mathbb{F}_{p^2} squaring	385	384	400	407
$\mathbb{F}_{p^2} \times \mathbb{F}_p$ multiplication	375	371	387	373
\mathbb{F}_{p^2} short coefficient reduction	73	73	73	108
\mathbb{F}_{p^2} inversion	135255	129210	137913	126077
Miller loop (incl. two final addition steps)	2,279,095	2,274,841	2,337,213	2,440,660
optimal ate pairing	4,416,425	4,379,912	4,762,474	4,784,524

Table 2. Cycle counts of relevant operations on different machines. Curve parameters: $p = 36u^4 + 36u^3 + 24u^2 + 6u + 1$, with $u = v^3$ and $v = 1868033$, BN curve: $y^2 = x^3 + 3$ over \mathbb{F}_p .

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